RIEGL miniVUX-3UAV

- 100 kHz / 200 kHz / 300 kHz Laser PRR selectable
- measurement rate up to 200,000 measurements/sec
- scan speed up to 100 scans/sec
- very compact & lightweight (1.55 kg / 3.4 lbs)
- up to 360° field-of-view
- robust aluminum housing, ready to be mounted on multi-rotor, rotary-wing, and fixed-wing UAVs
- makes use of RIEGL's unique echo signal digitization and online waveform processing
- multiple target capability up to 5 target echoes per laser shot
- mechanical and electrical interface for IMU mounting
- exceptionally well suited to measure in snowy and icy terrains
- user-friendly, application- and installation-oriented solutions for integration

The *RIEGL* miniVUX-3UAV is an extremely lightweight airborne laser scanner, designed specifically for integration with UAS/UAV/RPAS. The sensor offers a selectable 100 kHz, 200 kHz, and 300 kHz laser pulse repetition rate (PRR). With 300 kHz PRR, it provides up to 100,000 measurements per second at 120° FoV and thus a dense point pattern on the ground for UAV-based applications that require the acquisition of small objects.

The small and sophisticated design of the stable aluminum housing offers various integration possibilities with platforms that offer restricted space or payload capabilities. The 360° field of view allows complete acquisition of the environment.

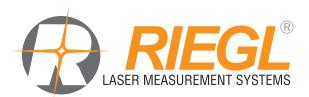
An easy-to-remove SD card for data storage, and/or the option for streaming the scan data via LAN-TCP/IP interface, in combination with the modest power consumption of the scanner, enable straight-forward integration with most UAS/UAV/RPAS types.

The *RIEGL* miniVUX-3UAV makes use of *RIEGL's* unique Waveform-LiDAR technology, allowing echo digitization and online waveform processing. Multi-target resolution is the basis for penetrating even dense foliage. As a further special feature, the wavelength is optimized for the measurement of snowy and icy terrain.

In addition to the stand-alone version of the miniVUX-3UAV, *RIEGL* also offers fully-integrated system solutions.

Typical applications include

- Agriculture & Forestry
- Glacier and Snowfield Mapping
- Archeology and Cultural Heritage Documentation
- Construction-Site Monitoring
- Landslide Monitoring



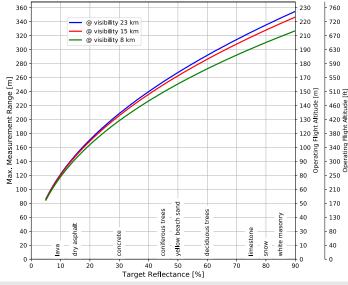
visit our website www.riegl.com

Unmanned Laser Scanning

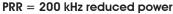
Data Sheet

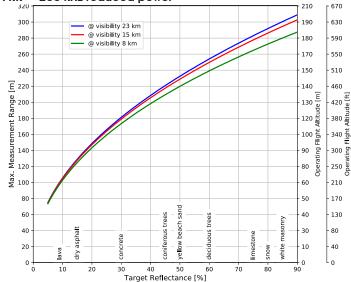
Maximum Measurement Range vs. Target Reflectance RIEGL miniVUX®-3UAV

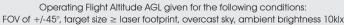
PRR = 100 kHz

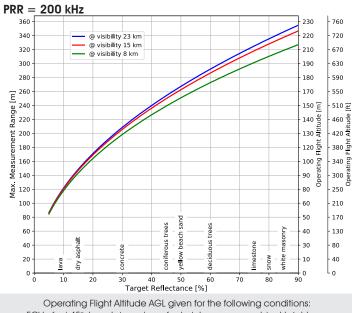




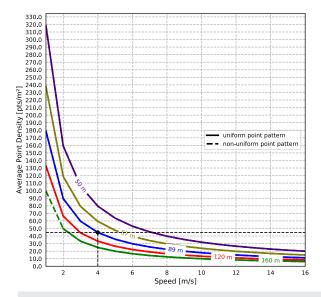


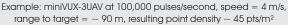


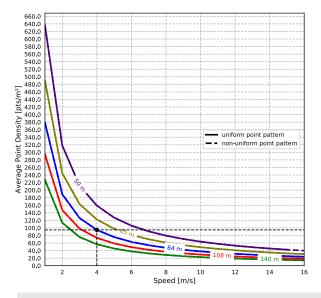




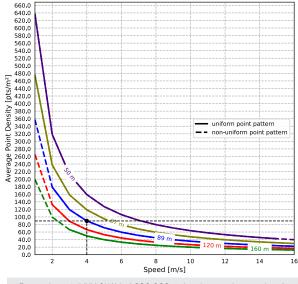
FOV of $+/-45^{\circ}$, target size \geq laser footprint, average ambient brightness





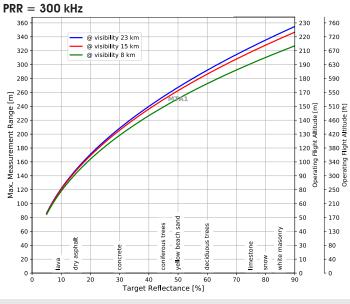


Example: miniVUX-3UAV at 200,000 pulses/second, speed = 4 m/s, range to target = \sim 85 m, resulting point density \sim 95 pts/m²

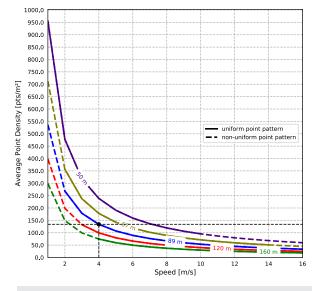


Example: miniVUX-3UAV at 200,000 pulses/second, speed = 4 m/s, range to target = \sim 90 m, resulting point density \sim 90 pts/m²

Maximum Measurement Range vs. Target Reflectance RIEGL miniVUX®-3UAV



Operating Flight Altitude AGL given for the following conditions: FOV of +/-45°, target size \geq laser footprint, average ambient brightness



Example: miniVUX-3UAV at 300,000 pulses/second, speed = 4 m/s, range to target = \sim 90 m, resulting point density \sim 135 pts/m²

RIEGL miniVUX-SYS System Integration Options

Besides of the stand-alone miniVUX-3UAV LiDAR engine, *RIEGL* offers also system solutions, combining the miniVUX-3UAV with IMU/GNSS systems of different performance and of different form factors as well as optional RGB camera systems. Additionally, a special add-on to the miniVUX-SYS allows for straight forward integration with your multi-rotor UAV, e.g. a DJI Matrice M600 / M300 RTK.

Please contact sales@riegl.com to get more detailed information.

RIEGL miniVUX-3UAV with APX-15 UAV¹⁾



- IMU/GNSS unit integrated with LiDAR engine
- total weight approx. 2 kg
- interfaces for up to 2 cameras
- suited for integration into fixed-wing UAVs

RIEGL miniVUX-3UAV with APX-20 UAV (IMU82/IMU90)¹⁾



- higher-grade IMU/GNSS unit partly integrated (IMU82) respectively fully integrated (IMU90) with LiDAR engine
- total weight approx. 2.5 kg
- interfaces for up to 2 cameras
- suited for integration into all types of UAVs

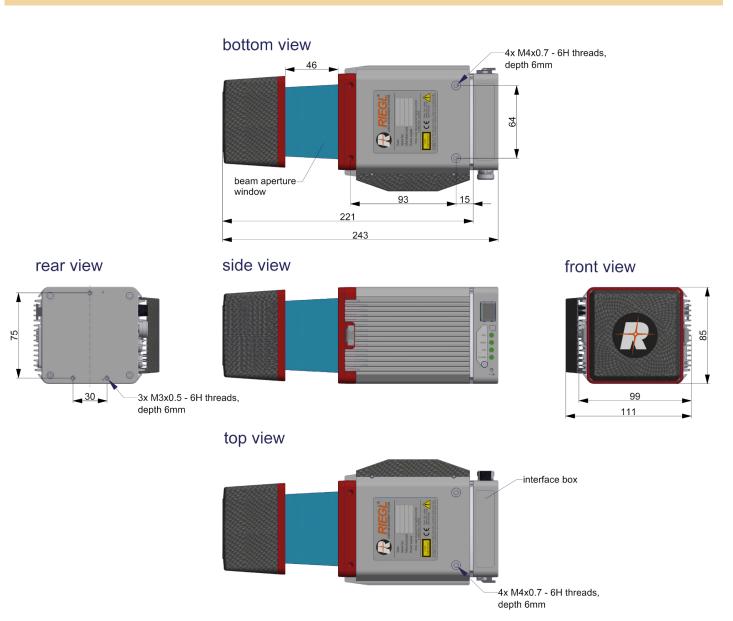
RIEGL Integration Kit 600 / 300



- add-on to the miniVUX-SYS coming with shock-absorbing mounting-kit, power supply module and cabling
- total weight approx. 0.7 kg / 0.35 kg (without sensor and camera)
- suited for integration into multi-rotor UAVs

1) See technical details in the corresponding Applanix data sheet.

Dimensional Drawings *RIEGL* miniVUX®-3UAV Stand-Alone



all dimensions in mm

RIEGL miniVUX[®]-3UAV Camera Options

RIEGL miniVUX-3UAV LiDAR Sensor equipped with APX-15 UAV¹)



with two Sony Alpha 6000 cameras (oblique mount)



with nadir-looking camera e.g. Sony Alpha 6000 camera or Sony A7R III or Sony A7R IV

RIEGL miniVUX-3UAV LiDAR Sensor equipped with APX-20 UAV (e.g. IMU82)¹⁾



with two Sony Alpha 6000 cameras (oblique mount)



with nadir-looking camera e.g. Sony Alpha 6000 camera or Sony A7R III or Sony A7R IV

integration of other 3rd party cameras possible ²⁾

See technical details in the corresponding Applanix data sheet.
 Multispectral camera, hyperspectral camera, thermal imaging sensor – more information on request.

Technical Data RIEGL miniVUX®-3UAV

Laser Product Classification

Class 1 Laser Product according to IEC 60825-1:2014 The following clause applies for instruments delivered into the United States: Complies with 21 CFR 1040.10 and 1040.11 except for conformance with IEC 60825-1 Ed.3., as described in Laser Notice No. 56, dated May 8, 2019.

CLASS 1 LASER PRODUCT

Range Measurement Performance

Measuring Principle

time of flight measurement, echo signal digitization, online waveform processing

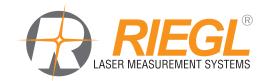
Laser Pulse Repetition Rate PRR $^{\mbox{\tiny 1}\mbox{\tiny }}$	100 kHz	200 kHz reduced power	200 kHz	300 kHz
Max. Measuring Range ²⁾ natural targets $\rho \ge 20$ % natural targets $\rho \ge 60$ % natural targets $\rho \ge 80$ %	170 m 290 m 330 m	150 m 250 m 280 m	170 m 290 m 330 m	170 m 290 m 330 m
Typ. Operating Flight Altitude AGL $^{1) 3)}$ natural targets $\rho \ \geq \ 20 \ \%$ natural targets $\rho \ \geq \ 60 \ \%$	100 m (330 ft) 160 m (525 ft)	85 m (280 ft) 140 m (460 ft)	100 m (330 ft) 160 m (525 ft)	100 m (330 ft) 160 m (525 ft)
Max. Number of Targets per Pulse ⁴⁾	5	5	5	5

Rounded values.
 Typical values for average conditions. Maximum range is specified for flat targets with size in excess of the laser beam diameter, perpendicular angle of incidence, and for atmospheric visibility of 23 km. In bright sunlight, the max. range is shorter than under overcast sky.
 Flat terrain assumed, scan angle ±45° FOV

4) If more than one target is hit, the total laser transmitter power is split and, accordingly, the achieveable range is reduced.

 If more than one target is hit, the total laser transmitter power is sp 	nif ana, accordingly, the achieveable range is reduced.	
Minimum Range Accuracy ^{5) 7)} Precision ^{6) 7)} Laser Pulse Repetition Rate ¹⁾ Max. Effective Measurement Rate ¹⁾ Echo Signal Intensity Laser Wavelength Laser Beam Divergence ⁸⁾ Laser Beam Footprint	2 m 15 mm 10 mm 100 kHz / 200 kHz / 300 kHz (selectable) up to 200 000 meas./sec. (@ 200 kHz PRR reduced power & 360° FOV) for each echo signal, high-resolution 16 bit intensity information is provided near infrared 1.6 x 0.5 mrad 160 mm x 50 mm @ 100 m	
 Accuracy is the degree of conformity of a measured quantity to its actual (true) value. Precision, also called reproducibility or repeatability, is the degree to which further measurements show the same result. 	 One sigma @ 50 m range under <i>RIEGL</i> test conditions. Measured at 50% peak intensity, 1.6 mrad corresponds to an increase of 160 mm of beam diameter per 100 m distance. 	
Scanner Performance Scanning Mechanism Field of View (selectable)	rotating mirror 360° @ 100 kHz, 200 kHz reduced power 180° @ 200 kHz 120° @ 300 kHz	
Scan Speed (selectable) Angular Step Width $\Delta \phi$ (selectable) between consecutive laser shots	10 - 100 scans/sec ⁹) @ 100 kHz, 200 kHz reduced power 20 - 100 scans/sec ⁹) @ 200 kHz 30 - 100 scans/sec ⁹) @ 300 kHz 0.018° $\leq \Delta \phi \leq 0.36^{\circ}$	
Angle Measurement Resolution	0.001°	
9) equivalent to revolutions per second		
Interfaces Configuration, Scan Data Output & Communication with External Devices GNSS Interface ¹⁰⁾	2 x LAN 10/100/1000 Mbit/sec WLAN IEEE 802.11 a/b/g/n Serial RS-232 interface for data string with GNSS-time information, TTL input for 1PPS synchronization pulse.	
General IO & Control ¹¹⁾	2 x TTL input/output, 1 x Remote on/off	
Camera Interface	2 x GNSS RS-232 Tx & PPS, Power, Trigger, Exposure	
Memory Card Slot	for SDHC/SDXC memory card 32 GByte (can be upgraded to 64 GByte)	
10) internally available (not available with standard interface box)	11) 1x externally available with standard interface box	
General Technical Data Power Supply Input Voltage / Consumption Main Dimensions (L x W x H) / Weight with Cooling Fan without Cooling Fan Humidity Protection Class Temperature Range ¹²	11 - 34 V DC / typ. 18 W @ 100 scans/sec 243 x 111 x 85 mm / approx. 1.6 kg 243 x 99 x 85 mm / approx. 1.55 kg max. 80 % non condensing @ 31°C IP64, dust and splash-proof -10°C up to +40°C (operation) / -20°C up to +50°C (storage)	
12) Continuous operation at ambient temperature of ≥ 30°C (≥ 86°F) requires a minimum amount of air flow at approx. 3 m/s. For applications where a 3 m/s air flow along the cooling fins cannot be presented the result of the form the table at the result.		

be guaranteed, the cooling fan has to be used.



RIEGL Laser Measurement Systems GmbH Horn, Austria

Phone: +43 2982 4211 | www.riegl.com **RIEGL USA Inc.** Winter Garden, Florida, USA Phone: +1 407 248 9927 | www.rieglusa.com

RIEGL Japan Ltd. | www.riegl-japan.co.jp RIEGL China Ltd. | www.riegl.cn RIEGL Australia Pty Ltd. | www.riegl.com RIEGL Canada Inc. | www.rieglcanada.com RIEGL UK Ltd. | www.riegl.co.uk



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Data Sheet, RIEGL miniVUX-3UAV, 2022-09-27